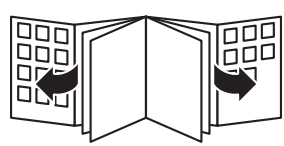
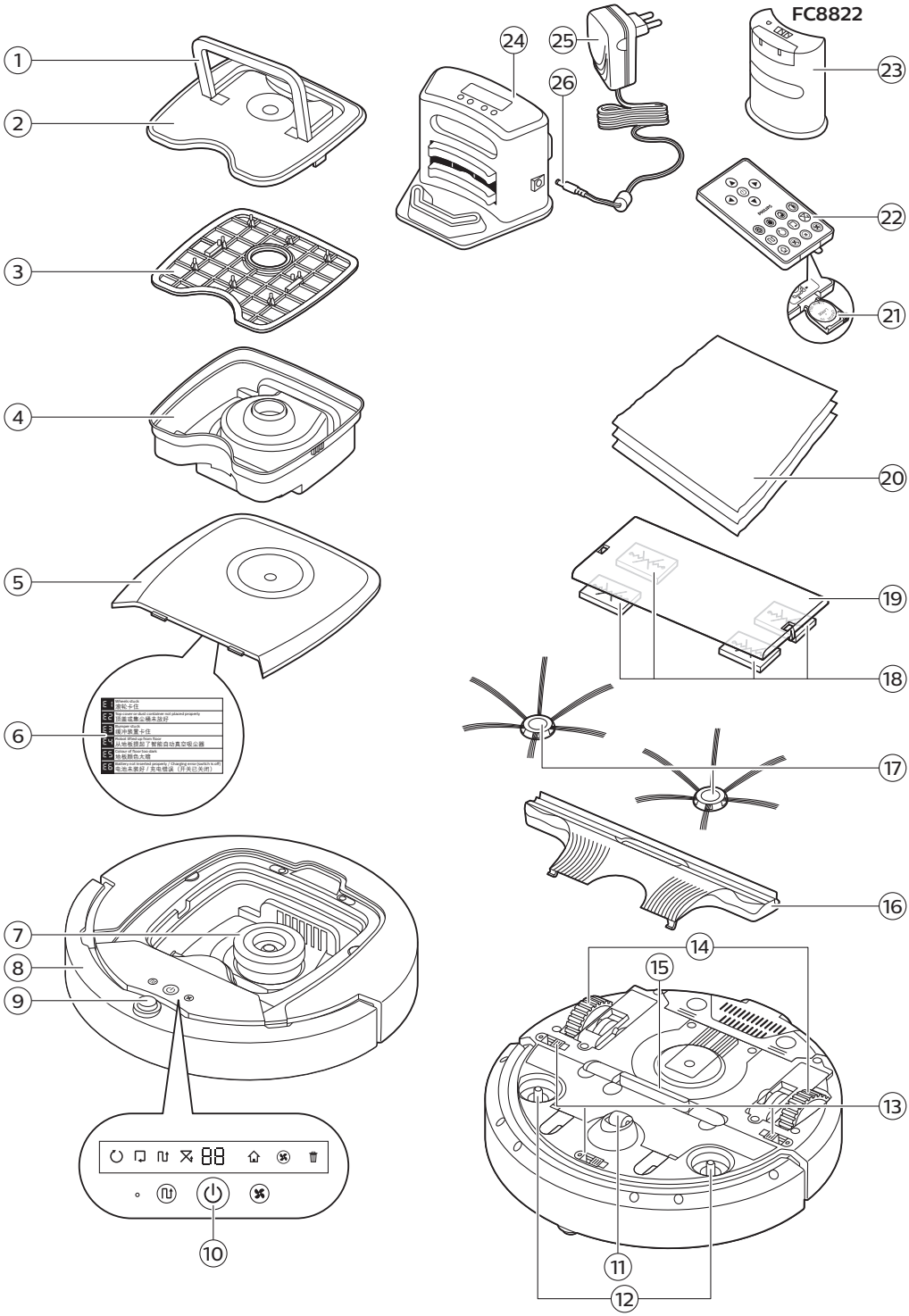
PHILIPS

FC8822, FC8812



FC8822



English 6
简体中文 19

Introduction

Congratulations on your purchase and welcome to Philips! To fully benefit from the support that Philips offers, register your product at **www.philips.com/welcome**.

General description

1 Handle of dust container lid
2 Dust container lid
3 Filter
4 Dust container
5 Top cover
6 Error codes table
7 Fan
8 Bumper
9 Docking station sensor
10 On/off button
11 Front wheel
12 Side brush shafts
13 Drop-off sensors
14 Wheels
15 Suction opening
16 TriActive XL nozzle
17 Side brushes
18 Fixation blocks for dry wipes
19 Dry wipe holder
20 Dry wipes
21 Battery holder
22 Remote control
23 Invisible wall (FC8822)
24 Docking station
25 Adapter
26 Small plug

Display and remote control

Display of robot

1 Spiral mode indicator
2 Wall-following mode indicator
3 Zigzag pattern mode indicator
4 Random mode indicator
5 Charging indicator and cleaning time indicator (see 'Using the cleaning time buttons')
6 Docking icon
7 Fan speed indicator
8 Dustbin full indicator
9 Sound sensor
10 Mode selection button
11 Start/stop button
12 Fan speed button

Remote control

1 Navigation buttons and start/stop (Fig. 3)

2 Cleaning time buttons
3 Cleaning mode buttons
4 Fan speed buttons
5 Docking button

Control panel of docking station

1 Display with time, day and programming indications (Fig. 4)
2 Adjusting and setting buttons

How your robot works

What your robot cleans

This robot is equipped with features that make it a suitable cleaner to help you clean the floors in your home.

The robot is especially suitable for cleaning hard floors, such as wooden, tiled or linoleum floors. It may experience problems cleaning soft floors, such as carpet or rugs. If you use the robot on a carpet or rug, please stay close by the first time to see if the robot can deal with this type of floor. The robot also needs supervision when you use it on very dark or shiny hard floors.

How your robot cleans

Cleaning system

The robot has a 3-stage cleaning system to clean your floors efficiently.

1 The two side brushes help the robot clean in corners and along walls. They also help to remove dirt from the floor and move it towards the suction opening (Fig. 5).
2 The suction power of the robot picks up loose dirt and transports it through the suction opening into the dust container.
3 The robot comes with a dry wipe holder that allows you to clean your hard floor even more thoroughly with dry wipes.

Cleaning patterns

In its auto cleaning mode, the robot uses a fixed and automatic sequence of cleaning patterns to clean each area of the room optimally. It uses a Z-pattern (zigzag pattern), random pattern, wall-following pattern and spiral pattern successively (Fig. 6). It continues to move in this sequence of patterns to clean the room until the rechargeable battery runs low, or until it is switched off manually.

If the robot detects a particularly dirty area during its cleaning run, it switches to spiral mode and switches to turbo fan speed to ensure thorough dirt removal.

Note: You can also select each mode individually by pressing the appropriate button on the remote control (see 'Cleaning mode selection') or on the robot. The manually selected modes are only active for a couple of minutes. After that, the robot switches back to auto-cleaning mode.

How your robot avoids height differences

The robot has three drop-off sensors in its bottom. It uses these drop-off sensors to detect and avoid height differences such as staircases (Fig. 7).

Note: It is normal for the robot to move slightly over the edge of a height difference, as its front drop-off sensor is located behind the bumper.

Caution: In some cases, the drop-off sensors may not detect a staircase or other height difference in time. Therefore monitor the robot carefully the first few times you use it, and when you operate it near a staircase or another height difference. It is important that you clean the drop-off sensors regularly to ensure the robot continues to detect height differences properly (see 'Cleaning and maintenance') .

Before first use

Mounting the side brushes

1 Unpack the side brushes and place the robot upside down on a table or on the floor.
2 Push the side brushes onto the shafts on the bottom of the robot (Fig. 8).

Note: Make sure you attach the side brushes properly. Press them onto the shaft until you hear them lock into position with a click.

Removing the tag from the remote control

The remote control works on a CR2025 coin-shaped battery. This battery is protected with a protection tag that has to be removed before use.

1 Pull the battery protection tag out of the battery compartment of the remote control. Now the remote control is ready for use (Fig. 9).

Preparing for use

Installing the docking station

1 Insert the small plug of the adapter into the socket on the docking station (1) and insert the adapter into the wall socket (2) (Fig. 10).
   - The display of the docking station comes on.
2 Place the docking station on a horizontal, level floor against the wall.

Note: Make sure that there are no obstacles or height differences 80 cm in front, 30 cm to the right and 100 cm to the left of the docking station (Fig. 11).

Tip: To ensure the docking station stays firmly in the selected spot, fasten it to the wall with screws or with two strips of double-sided tape.

Important note: deep sleep mode

In deep sleep mode, the robot does not respond at all when you press a button. To reactivate the robot when it is in deep sleep mode:

1 Press the start/stop button on the robot for one second to switch the robot from deep sleep mode to standby mode.
2 Press the start/stop button on the robot (Fig. 17) briefly or press the start/stop button on the remote control to start cleaning.
3 If the robot does not start cleaning, place it on the plugged-in docking station to recharge its rechargeable battery.

The robot enters deep sleep mode when you press the start/stop button for 5 seconds. It may also enter the deep sleep mode when its battery is empty. The battery may, for instance, run empty if the robot is unable to find its docking station.

Charging

When charging for the first time and when the rechargeable battery of the robot is empty, the charging time is four hours.

Your robot can be charged on the docking station, either manually or automatically during use.

Note: When the rechargeable battery is fully charged, your robot can clean for up to 120 minutes

Charging automatically during use

1 When the robot has finished cleaning or when only 15% of the battery power remains, it automatically searches for the docking station to recharge. When the robot searches for the docking station, the light in the start/stop button turns orange (Fig. 15).
2 When the rechargeable battery is fully charged, the start/stop button lights up green continuously.

Charging on the docking station

1 Place the robot on the plugged-in docking station (Fig. 12).
2 The start/stop button starts flashing green. Because this is the first time you charge the robot, the display of the robot shows the charging indicator (Fig. 13).
3 When the rechargeable battery is fully charged, the start/stop button lights up green continuously (Fig. 14).

Using your robot

Preparing the room for a cleaning run

Before you start the robot on its cleaning run, make sure that you remove all loose and fragile objects from the floor. Also remove all cables, wires and cords from the floor.

Functions of the start/stop button

The start/stop button has the following functions (Fig. 16):

How you press start/stop button	How robot responds
Press start/stop button for 1 second	Robot switches from sleep mode to standby
Press start/stop button briefly	Robot starts or stops cleaning
Press start/stop button for 5 seconds	Switches robot on or off.

User interface signals and their meaning

The robot has a display and a start/stop button gives light signals. The table below explains the meaning of the signals.

Signal	Description of signal	Meaning of signal
	The start/stop button is continuously green.	The robot is ready to clean.

Signal	Description of signal	Meaning of signal
	The start/stop button flashes slowly green and the display on the robot shows a moving blue light (the charging indicator).	The robot is charging.
	The start/stop button is continuously orange.	The rechargeable battery is low and the robot is searching for the docking station.
	The start/stop button is continuously red.	The rechargeable battery of the robot is almost empty.
	The start/stop button is continuously red and the display shows an error code.	Please consult the error code table below to understand the meaning of the error code.

Error codes

Error code	Possible cause	Solution
E1	Wheels stuck	Remove robot from the obstacle and press the starts/stop button to resume cleaning.
E2	Top cover or dust container not placed properly	Place the dust container in and the top cover on the robot properly. The error code disappears from the display automatically.
E3	Bumper stuck	Remove the robot from the obstacle. The error code disappears from the display automatically.
E4	Robot lifted from floor	Put the robot back on the floor to make the error code disappear.
E5	Color of floor too dark	Place robot on a lighter area of the floor. Clean the drop-off sensors.
E6	Problem with the battery	Please contact the Consumer Care Center to have the problem examined.

Clap response

If you do not see the robot, you can locate it by clapping your hands once. The robot will respond by beeping and by lighting up all icons on its display.

The clap response is enabled when the robot enters sleep mode in the following situations:

- when it stops cleaning due to an error
- when it is unable to find its docking station within 20 minutes

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Starting and stopping

1 Press the start/stop button on the robot (Fig. 17) or on the remote control (Fig. 18). The start/stop button is continuously green and the robot starts cleaning.

2 The robot cleans in the auto-cleaning mode until its battery runs low. In the auto-cleaning mode, it follows repeated sequences of Z-pattern, random, wall-following and spiral patterns (Fig. 6).

Note: To select an individual mode, press one of the mode buttons on the remote control or on the robot (see 'Cleaning mode selection').

3 When the battery runs low, the start/stop button turns red and the robot searches for the docking station to recharge (Fig. 15).
4 You can also press the start/stop button to interrupt or stop the cleaning run. If you press the start/stop button again and there is still enough energy in the rechargeable battery, the robot continues cleaning in the auto-cleaning mode.
5 To make the robot return to the docking station before the rechargeable battery runs low, press the docking button on the remote control. All icons on the display of the robot disappear except for the docking icon, which lights up bright blue while the robot returns to the docking station (Fig. 19).

Cleaning mode selection

Next to the auto-cleaning mode, this robot has four individual cleaning modes that can each be activated by pressing the appropriate button on the remote control or on the robot.

Note: The manually selected modes are only active for a couple of minutes. After that, the robot switches back to auto-cleaning mode.

Z-pattern mode

In Z-pattern mode, the robot cleans by making Z-shaped loops through the room to clean large areas (Fig. 20).

Random mode

In this mode, the robot cleans the room in a mixed pattern of straight and crisscross movements (Fig. 21).

Wall-following mode

In this mode, the robot follows the walls of the room to give the area alongside the walls an extra clean (Fig. 22).

Spiral mode

In this mode, the robot moves in a spiral pattern to clean a small area. If the dust detection sensor detects dirt, the robot automatically switches the fan to turbo speed (Fig. 23).

Manual driving

1 Use the arrow buttons above and below and to the left and right of the start/stop button on the remote control to navigate the robot through the room (Fig. 24).

Note: Be careful when you drive the robot manually close to height differences and staircases.

Note: The vacuuming function and the side brushes only work when the robot is driven forward. The left, right or back buttons are only for maneuvering the robot.

Using the cleaning time buttons

- By default, the robot cleans in auto cleaning mode until its rechargeable battery runs low. The robot will then automatically return to its docking station. If you selected one of the other cleaning times (see below), you can switch back to the default mode by pressing the maximum cleaning time button on the remote control (Fig. 25).
- The other cleaning time buttons on the remote control allow you to let the robot operate for 60, 45 and 30 minutes respectively (Fig. 26). The cleaning time indicator on the display shows the cleaning time set. When the cleaning time is finished, the robot returns to its docking station. The docking icon will turn bright blue on the display.
- If you do not want the robot to return to the docking station at the end of the cleaning time, press the cleaning time button twice. The docking icon disappears from the display. When the cleaning time is finished, the robot stops.

Operating the docking station

Setting clock time and day

If you want to use cleaning programs, you have to set the clock time and the day of the week on the display of the docking station first.

Note: For the pictures that belong to the steps below, see the pages at the back of this manual.

1 Press the set button. The set mode indicator and the clock time indicator start flashing.
2 Press the select button once. The hour indication starts flashing.
3 Use the + and - buttons on the docking station to set the hour.The set hour appears on the display.
4 Press the select button to confirm the hour set. The minutes indication starts flashing.
5 Use the + and - buttons on the docking station to set the minutes. The set minutes appear on the display.
6 Press the select button to confirm the minutes set. The indication 'Su' for Sunday starts flashing.
7 Use the + and - buttons on the docking station to set the current day of the week.
8 Press the select button to confirm the day of the week.
9 Press the set button to confirm the clock time and day of the week setting. Both the set mode indicator and the clock time indicator stop flashing and turn solid.

Programming cleaning times

If you have set the time and the day of the week on the display of the docking station, you can program cleaning times for your robot.

Note: For the pictures that belong to the steps below, see the pages at the back of this manual.

The programming options available are:

Program	Indications on display
Cleaning every day	All day indications are on
Cleaning on weekdays	Mo to Fri indications are on
Cleaning on 2 consecutive days	Indications of 2 days are on, e.g. Fri and Sa
Cleaning 1 day a week	Indication of selected day is on

1 Press the set button. The set mode indicator and the cleaning program indicator start flashing.
2 Press the select button once. The hour indication starts flashing.

3 Use the + and - buttons on the docking station to set the hour. The set hour appears on the display.
4 Press the select button to confirm the hour set. The minutes indication starts flashing.
5 Use the + and - buttons on the docking station to set the minutes. The set minutes appear on the display.
6 Press the select button to confirm the minutes set. The indication 'Su' for Sunday starts flashing.
7 Use the + and - buttons on the docking station to toggle between cleaning programs (see the table above for the programming options available).
8 Press the select button to confirm the program selected.
9 Press the set button to confirm the programming. Both the set mode indicator and the cleaning program indicator stop flashing and turn solid.
10 When you have set a cleaning program, the display shows the cleaning program indicator and the day or days selected. If you leave the robot on standby and its rechargeable battery is fully charged, it will start cleaning at the programmed time on the programmed day or days.

Fan speed buttons

You can use the fan speed buttons to increase the fan speed to turbo or to switch off the fan. The default setting is normal fan speed (Fig. 27).
1 Press this button to switch off the fan
2 Press this button to switch on the fan at normal speed.
3 The turbo fan button increases the fan speed.

Using the dry wipe attachment

The dry wipe attachment is a feature that allows you to clean hard floors with dry wipes.

Note: If you use the dry wipe attachment, the robot may have trouble crossing thresholds or climbing onto rugs.

Preparing the dry wipe attachment for use

Turn the robot upside down and place it on the floor or on a table.
1 Place the dry wipe on a table and place the dry wipe attachment on the wipe with its fixation lugs pointing towards you (Fig. 28).
2 Fold both ends of the dry wipe around the dry wipe attachment and fasten the dry wipe onto the attachment by pushing the fixation blocks into the recesses (Fig. 29).
3 Insert the fixation lug of the dry wipe attachment into the opening just behind the wheel on one side of the robot and push until you hear it lock into place with a click. Then repeat these actions on the other side (Fig. 30).
4 Turn the robot and place it on the floor on its wheels with the dry wipe attachment touching the floor.

Using the robot with the dry wipe attachment

When the dry wipe attachment is attached, you can use the robot in any mode and on all hard floors. Do not use the dry wipe attachment on carpet or rugs.

Removing the dry wipe attachment

1 Remove the dry wipe attachment as soon as you have finished wiping the floor. To do so, turn the robot upside down and place it on the floor or on a table.
2 Push one end of the dry wipe attachment towards the wheel on the other side of the robot to release it. Then pull the attachment off the robot (Fig. 31).

3 If the dry wipe is to dirty to use again, pull the fixation blocks out of the dry wipe attachment and dispose of the dry wipe.

Note: You cannot rinse or wash the dry wipes.

Using the invisible wall (FC8822 only)

You can use the invisible wall to prevent the robot from entering a room or area that you want to keep it out of.

Placing the batteries in the invisible wall

The invisible wall operates on four AA batteries.

1 Push the two release tabs at the bottom of the back cover (1) and slide the back cover upwards and off the invisible wall (2) (Fig. 32).
2 Take four new AA batteries from the pack and insert them into the battery compartment of the invisible wall (Fig. 33).

Note: Make sure the + and - poles of the batteries point in the right direction.

3 Slide the back cover onto the invisible wall again (Fig. 34).

Positioning the invisible wall to stop the robot

1 Place the unit at a point you do not want the robot to cross, e.g at an open door to a room that is off-limits to the robot (Fig. 35).
2 Switch on the invisible wall with the on/off slide on top of the unit (Fig. 36).
3 Start the robot.
4 When the robot comes too close to the invisible wall, the light on the invisible wall starts flashing and the invisible wall emits a beam of infrared light. This beam of infrared light makes the robot change its course and move away from the invisible wall (Fig. 37).

Note: If you use the invisible wall, regularly check if the batteries still contain sufficient power. You can check this by switching the virtual wall off and on again. If there is enough energy in the batteries, the LED on the invisible wall will light up briefly.

Cleaning and maintenance

Cleaning the robot

To maintain good cleaning performance, you have to clean the drop-off sensors, the wheels, the side brushes and the suction opening from time to time.

1 Place the robot upside down on a flat surface
2 Use a brush with soft bristles (e.g. a toothbrush) to remove dust or fluff from the drop-off sensors (Fig. 38).

Note: It is important that you clean the drop-off sensors regularly. If the drop-off sensors are dirty, the robot may fail to detect height differences or staircases.

3 Use a brush with soft bristles (e.g. a toothbrush) to remove dust or fluff from the front wheel and side wheels (Fig. 39).
4 To clean the side brushes, grab them by the bristles and pull them off their shafts (Fig. 40).
5 Remove fluff, hairs and threads from the shaft and from the side brush with a soft brush (e.g. a toothbrush) or a cloth (Fig. 41).

6 Check the side brushes and the bottom of the robot for any sharp objects that could damage your floor.
7 To remove the TriActive XL nozzle, insert your fingers into the slots in the bottom of the robot. There are arrows pointing to these slots. Press the catches holding the TriActive nozzle in place inwards to release them from the slots (1). Then pull the TriActive nozzle upward and off the robot (2) (Fig. 42).
8 Clean the suction opening with a soft brush (e.g. a toothbrush) (Fig. 43).
9 Remove all visible dirt from the TriActive nozzle before you place it back.
10 To place the TriActive nozzle, first insert the small lugs on the front into the tiny slots on either side of the front wheel (1). Then press the catches of the TriActive nozzle inwards to lock them into the slots in the bottom of the robot (2). Finally, check if the nozzle can still move a few millimeters up and down freely (Fig. 44).
11 Push the side brushes onto the shafts on the bottom of the robot again (Fig. 8).

Emptying and cleaning the dust container

Empty and clean the dust container when the dust container full indicator lights up continuously.

1 Remove the cover.
2 Pull up the handle of the dust container lid and lift the dust container out of the dust container compartment.

Note: When you remove or reinsert the dust container, take care not to damage the blades of the motor fan.

3 Carefully lift the lid off the dust container (1) and take out the filter (2) (Fig. 45).
4 Shake the dust container over a dustbin to empty it. Clean the filter and the inside of the dust container with a cloth or a toothbrush with soft bristles. Also clean the suction opening in the bottom of the dust container.

Caution: Do not clean the dust container and the filter with water or in the dishwasher.

5 Put the filter back into the dust container (1). Then place the lid on the dust container(2) (Fig. 47).
6 Put the dust container back into the dust container compartment and put the top cover back on the robot (Fig. 48).

Caution: Always make sure the filter is present inside the dust container. If you use the robot without the filter inside the dust container, the motor will be damaged.

Ordering accessories

To buy accessories or spare parts, visit **www.shop.philips.com/service** or go to your Philips dealer. You can also contact the Philips Consumer Care Center in your country (see the international warranty leaflet for contact details).

Replacement

Replacing the filter

Replace the filter if it is very dirty or damaged. You can order a new filter kit under type number FC8066. See 'Emptying and cleaning the dust container' in chapter 'Cleaning and maintenance' for instructions on how to remove the filter from the dust container and how to place it in the dust container.

Replacing the side brushes

Replace the side brushes after some time to ensure proper cleaning results.

Always replace the side brushes when you notice signs of wear or damage. We also recommend that you replace both side brushes at the same time. You can order spare side brushes as part of replacement kit FC8068. This kit also contains two filters and three dry wipes.

1 To replace the side brushes, grab the old side brushes by the bristles and pull them off their shafts (Fig. 40).
2 Push the new side brushes onto the shafts (Fig. 8).

Replacing dry wipes

You can order new dry wipes. They are part of replacement kit FC8068. This replacement kit also contains two side brushes and two filters.

Replacing the battery of the remote control

The remote control works on a CR2025 coin-shaped battery. Replace the battery when the robot no longer responds when you press the buttons on the remote control.

1 Hold the remote control upside down. Push the release button on the battery holder and at the same time slide the battery holder out of the remote control (Fig. 49).
2 Remove the empty battery from the battery holder and place a new battery in the battery holder. Then slide the battery holder back into the remote control (Fig. 50).

Replacing the rechargeable battery

The rechargeable battery of the robot may only be replaced by qualified service engineers. Take the robot to an authorized Philips service center to have the battery replaced when you can no longer recharge it or when it runs out of power quickly. You can find the contact details of the Philips Consumer Care Center in your country in the international warranty leaflet or go to www.philips.com/support.

Recycling

- Do not throw away the product with the normal household waste at the end of its life, but hand it in at an official collection point for recycling. By doing this, you help to preserve the environment.
- This product contains a built-in rechargeable battery which shall not be disposed of with normal household waste. Please take your product to an official collection point or a Philips service center to have a professional remove the rechargeable battery.
- Follow your country's rules for the separate collection of electrical and electronic products and rechargeable batteries. Correct disposal helps prevent negative consequences for the environment and human health.

Removing the rechargeable battery

Warning: Only remove the rechargeable battery when you discard the appliance. Make sure the battery is completely empty when you remove it.

To remove the rechargeable battery, follow the instructions below. You can also take the robot to a Philips service center to have the rechargeable battery removed. Contact the Philips Consumer Care Center in your country for the address of a service center near you.

1 Start the robot from a place somewhere in the room and not from the docking station.

2 Let the robot run until the rechargeable battery is empty to make sure that the rechargeable battery is completely discharged before you remove it and dispose of it.
3 Undo the screws of the battery compartment lid and remove the lid (Fig. 51).
4 Lift out the rechargeable battery and disconnect it (Fig. 52).
5 Take the robot and the rechargeable battery to a collection point for electrical and electronic waste.

Troubleshooting

This chapter summarizes the most common problems you could encounter with the appliance. If you are unable to solve the problem with the information below, visit **www.philips.com/support** for a list of frequently asked questions or contact the Consumer Care Center in your country.

Troubleshooting

Problem	Possible cause	Solution
The robot does not start cleaning when I press the start/stop button.	The rechargeable battery is empty.	Charge the rechargeable battery.
The robot does not clean properly.	The bristles of one or both side brushes are crooked or bent.	Soak the brush or brushes in warm water for a while and let them dry on a flat surface before you mount them on the robot again. If this does not restore the bristles to their proper shape, replace the side brushes (see 'Replacing the side brushes').
	The filter in the dust container is dirty.	Clean the filter in the dust container with a cloth or a toothbrush with soft bristles.You can also clean the filter and dust container with a regular vacuum cleaner at a low suction power setting.
		If brushing or vacuuming does not help to clean the filter, replace the filter with a new one. We advise you to replace the filter at least once a year.
	The suction opening in the bottom of the dust container is clogged.	Clean the suction opening (see 'Cleaning and maintenance').
	The front wheel is jammed with hair or other dirt.	Clean the front wheel (see 'Cleaning and maintenance').
	The robot is cleaning a very dark or shiny surface, which triggers the drop-off sensors.This causes the robot to move in an unusual pattern.	Press the start/stop button and then move the robot to a lighter colored piece of the floor. If the problem continues to occur on lighter colored floors, please go to www.philips.com/support or contact the Consumer Care Center in your country.

Problem	Possible cause	Solution
	The robot is cleaning a floor that reflects sunlight quite strongly. This triggers the drop-off sensors and causes the robot to move in an unusual pattern.	Close the curtains to block sunlight from entering the room. You can also start cleaning when the sunlight is less bright.
The on/off button lights up red continuously and there is an error code on the display.	Your robot is giving an error signal.	Check the error codes table for the meaning of the code (see 'Error codes').
The robot is moving in circles.	The robot is in spiral mode.	This is normal behavior. The spiral mode can be activated when a lot of dirt is detected on the floor for a thorough clean. It is also part of the auto cleaning mode. After approximately one minute the robot resumes its normal cleaning pattern. You can also stop the spiral mode by selecting a different cleaning mode on the remote control.
The robot cannot find its docking station.	There is not enough room for the robot to navigate towards the docking station.	Try to find another place for the docking station (see 'Installing the docking station').
	The robot is still actively searching.	Give the robot around 20 minutes to return to the docking station.
	You may have deactivated the automatic docking function of the robot by pressing the cleaning time button twice. In that case, the docking icon is no longer visible on the display and the robot stops when the cleaning time is finished.	Press the start/stop button for 5 seconds to restart the robot. The docking function is automatically activated again. You can also press the cleaning time button twice to reactivate the docking function. The docking icon will reappear on the display. To make the robot return to the docking station, press the docking button.

简介

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基本说明

1 集尘盒盖手柄
2 集尘盒盖
3 过滤网
4 集尘盒
5 上盖
6 错误代码表
7 风叶
8 缓冲装置
9 底座传感器
10 开/关按钮
11 前轮
12 侧毛刷轴
13 跌落传感器
14 滚轮
15 吸口
16 TriActive XL 吸嘴
17 侧毛刷
18 干巾固定块
19 干巾架
20 干巾
21 电池舱
22 遥控器
23 隐形墙 (FC8822)
24 底座
25 适配器
26 小插头

显示屏和遥控器

智能自动真空吸尘器显示屏

1 螺旋模式指示灯
2 沿墙模式指示灯
3 之字形方向图模式指示灯
4 随机模式指示灯
5 充电指示灯和清洁时间标志 (请参见 '使用清洁时间按钮')
6 插接图标
7 风速指示灯
8 垃圾箱已满指示灯
9 声音传感器
10 模式选择按钮
11 启动/停止按钮
12 风速按钮

遥控器

1 导航按钮和启动/停止 (图 3)

2 清洁时间按钮
3 清洁模式按钮
4 风速按钮
5 插接按钮

底座的控制面板

1 带时间、日期和设定指示 (图 4)的显示屏
2 调节和设置按钮

扫地机器人如何工作

扫地机器人清洁哪些物体

本扫地机器人具有许多功能，是一款适合帮助您在家中清洁地板的理想清洁工具。

此扫地机器人尤其适合清洁硬地板，例如木制、瓷砖或油毡地板。 清洁软地板时可能会出现问题，例如地毯或地垫。 如果您在地毯或地垫上使用扫地机器人，请在第一次使用之前先留心观察扫地机器人是否能够处理这种类型的地板。 另外，当您在极暗或有光泽的坚硬地板上使用扫地机器人时，需要对其加以监控。

智能自动真空吸尘器如何清洁

清洁系统

智能自动真空吸尘器利用 3 重清洁系统来高效清洁地面。

1 两个侧毛刷有助于智能自动真空吸尘器清洁角落以及墙角沿线。 它们还可帮助清除地板上的灰尘，并将其移向吸口 (图 5)。
2 智能自动真空吸尘器的吸力可吸入松动的污垢，然后通过吸口将污垢输送到集尘桶。
3 智能自动真空吸尘器配有干巾架，用干巾可以更彻底地清洁硬地板。

清洁方向图

在自动清洁模式下，智能自动真空吸尘器会使用固定的自动清洁方向图顺序，以最适宜的方式清洁房间内的各个区域。 它会相继 (图 6)使用 Z 方向图（之字形方向图）、随机方向图、沿墙方向图和螺旋方向图。 然后继续按该顺序移动方向图来清洁房间，直至充电电池的电量不足或者将其手动关闭。

如果智能自动真空吸尘器在清洁操作时检测到特别脏的区域，其会切换至螺旋模式和强力风速以确保彻底清除污垢。

注意： 您还可以按遥控器 (请参见 '清洁模式选择')或智能自动真空吸尘器上的相应按钮，分别选择各个模式。手动选定的模式仅处于启用状态数分钟。 之后，智能自动真空吸尘器会切换回自动清洁模式。

智能自动真空吸尘器如何避开高度差

智能自动真空吸尘器底部配有三个跌落传感器。 智能自动真空吸尘器使用这些跌落传感器检测和避开楼梯 (图 7)等有高度差的地方。

注意： 智能自动真空吸尘器略微越过有高度差的边缘是正常现象，因为正面的跌落传感器位于缓冲装置后面。

警告： 在某些情况下，跌落传感器可能无法及时检测到楼梯或其他有高度差的地方。 因此，在最初几次使用以及在楼梯或其他有高度差的地方附近使用时，应密切监控智能自动真空吸尘器的工作。 请务必定期清洁跌落传感器，以确保智能自动真空吸尘器能继续正确 (请参见 '清洁和保养')检测到高度差。

首次使用之前

安装侧毛刷

1 打开侧毛刷包装，将智能自动真空吸尘器翻转过来，置于桌子或地板上。
2 将侧毛刷推入智能自动真空吸尘器 (图 8)底部的轴上。

注意： 确保您已正确安装侧毛刷。 将侧毛刷按在轴上，直至您听到其咔哒一声锁定到位。

取下遥控器上的保护贴

遥控器由 CR2025 纽扣电池供电。 该电池采用保护贴保护，使用前须取下。

1 抽出遥控器电池仓中的电池保护贴。 遥控器就可以使用 (图 9)了。

使用准备

安装底座

1 将适配器的小插头插入底座上的插座 (1)，将适配器插入电源插座 (2) (图 10)。
   - 底座的显示屏会亮起。
2 将底座放在靠墙的水平地板上。

注意： 确保底座 (图 11)正面 80 厘米、右侧 30 厘米、左侧 100 厘米没有障碍物或高度差。

提示： 为确保底座牢固地保持在选定位置，请用螺钉或两条双面胶带将其固定在墙上。

重要事项： 深度睡眠模式

如果智能自动真空吸尘器处于深度睡眠模式，则按下按钮后不会有任何反应。 要重新激活处于深度睡眠模式的智能自动真空吸尘器：

1 按住智能自动真空吸尘器上的启动/停止按钮一秒，将其从深度睡眠模式切换到待机模式。
2 短按智能自动真空吸尘器 (图 17)上的启动/停止按钮或按遥控器上的启动/停止按钮开始清洁。
3 如果智能自动真空吸尘器没有开始清洁，请将其置于接通电源的底座上，为充电电池充电。

按住启动/停止按钮 5 秒钟，智能自动真空吸尘器将进入深度睡眠模式。 当电池电量耗尽时，智能自动真空吸尘器也会进入深度睡眠模式。 如果智能自动真空吸尘器无法找到其底座，则电池可能会出现电量耗尽等情况。

充电

首次充电及智能自动真空吸尘器的充电电池电量耗尽时，需充电 4 小时。

智能自动真空吸尘器可以在底座上充电或在使用过程中手动或自动充电。

注意： 充电电池充满电后，智能自动真空吸尘器的清洁时间长达 120 分钟。

使用期间自动充电

1 当智能自动真空吸尘器完成清洁或电池电量仅剩 15% 时，它会自动搜索底座进行充电。 智能自动真空吸尘器搜索底座时，启动/停止按钮上的指示灯将变为橙色 (图 15)。
2 当充电电池充满电时，启动/停止按钮将持续亮起绿灯。

在底座上充电

1 将智能自动真空吸尘器置于接通电源的底座 (图 12)上。

2 启动/停止按钮开始呈绿色闪烁。 因为这是首次充电，智能自动真空吸尘器的显示屏会显示充电指示灯 (图 13)。
3 当充电电池充满电时，启动/停止按钮将持续 (图 14)亮起绿灯。

使用扫地机器人

准备房间以进行清洁操作

在启动智能自动真空吸尘器进行清洁操作之前，确保清除地板上的所有松散和易碎物体。 另外，移除地板上的所有电缆、电线和绳索。

启动/停止按钮的功能

启动/停止按钮具有以下功能 (图 16):

启动/停止按钮的按键方式	智能自动真空吸尘器的响应方式
按住启动/停止按钮 1 秒	智能自动真空吸尘器从睡眠模式切换到待机模式
短按启动/停止按钮	智能自动真空吸尘器开始或停止清洁
按住启动/停止按钮 5 秒	开关智能自动真空吸尘器。

用户界面信号及其含义

智能自动真空吸尘器通过显示屏和启动/停止按钮发出指示灯信号。 下表说明了这些信号的含义。

信号	信号描述	信号含义
	启动/停止按钮持续亮起绿灯。	吸尘器已做好清洁准备。
	启动/停止按钮缓慢闪烁绿色，智能自动真空吸尘器上的显示屏显示活动的蓝光（充电指示灯）。	吸尘器正在充电。
	启动/停止按钮持续亮起橙色。	充电电池电量不足，智能自动真空吸尘器正在搜索底座。
	启动/停止按钮持续亮起红色。	智能自动真空吸尘器的充电电池电量几乎耗尽。
	启动/停止按钮持续亮起红色，显示屏显示错误代码。	请查看下方的错误代码表了解错误代码的含义。

错误代码

错误代码	可能的原因	解决方法
E1	滚轮卡住	将智能自动真空吸尘器从障碍物处移开，按启动/停止按钮使其继续清洁。

错误代码	可能的原因	解决方法
E2	顶盖或集尘盒未放好	放入集尘盒并盖好智能自动真空吸尘器的上盖。 错误代码会从显示屏上自动消失。
E3	缓冲装置卡住	将智能自动真空吸尘器从障碍物处移开。 错误代码会从显示屏上自动消失。
E4	从地板提起了智能自动真空吸尘器	将智能自动真空吸尘器放在地板上以使错误代码消失。
E5	地板颜色太深	将智能自动真空吸尘器置于地板的浅色区。 清洁跌落传感器。
E6	电池问题	请联系客户服务中心检查问题所在。

拍手响应

如果您未见到智能自动真空吸尘器，则只需拍一次手即可以找到它。 智能自动真空吸尘器将通过发出蜂鸣音以及点亮显示屏上的所有图标做出响应。

在以下情况下，拍手响应会在智能自动真空吸尘器进入睡眠模式时启用:

- 当智能自动真空吸尘器因出错而停止清洁时
- 当智能自动真空吸尘器无法在 20 分钟内找到底座时

.

启动和停止

1 按智能自动真空吸尘器 (图 17)或遥控器 (图 18)上的启动/停止按钮。 启动/停止按钮持续亮起绿灯，智能自动真空吸尘器开始清洁。

2 智能自动真空吸尘器以自动清洁模式进行清洁，直至电池电量不足。 在自动清洁模式下，智能自动真空吸尘器按照之字形方向图、随机、沿墙和螺旋方向图 (图 6)的重复顺序进行清洁。

注意: 要选择单独模式，请按遥控器或智能自动真空吸尘器 (请参见 '清洁模式选择')上的任一模式按钮。

3 如果电池电量不足，启动/停止按钮将变为红色，智能自动真空吸尘器会搜索底座进行充电 (图 15)。

4 您也可以按启动/停止按钮中断或停止清洁操作。 如果再次按启动/停止按钮且充电电池仍有足够的电量，则智能自动真空吸尘器将继续以自动清洁模式进行清洁。

5 要使智能自动真空吸尘器在充电电池电量不足前返回到底座，请按遥控器上的插接按钮。 除了插接图标外，智能自动真空吸尘器显示屏上的所有图标都会消失，当吸尘器返回到底座 (图 19)时该图标会呈亮蓝色亮起。

清洁模式选择

除了自动清洁模式，这款智能自动真空吸尘器还提供四种单独清洁模式，每种模式均可通过按遥控器或智能自动真空吸尘器上的相应按钮启动。

注意: 手动选定的模式仅处于启用状态数分钟。 之后，智能自动真空吸尘器会切换回自动清洁模式。

之字形方向图模式

在 Z 方向图模式下，吸尘器将在整个房间中进行 Z 形环状运动以清洁大片区域 (图 20)。

随机模式

在该模式下，智能自动真空吸尘器将使用直线运动和交叉运动 (图 21)的混合模式清洁房间。

沿墙模式

在该模式下，智能自动真空吸尘器将沿着房间的墙壁对墙边区域进行特别清洁 (图 22)。

螺旋模式

在该模式下，智能自动真空吸尘器将按照螺旋方向图移动，以清洁小范围区域。 如果灰尘检测传感器检测到污垢，智能自动真空吸尘器会自动将风速切换至强力风速 (图 23)。

手动驱动

1 使用遥控器启动/停止按钮的上、下、左、右箭头按钮在房间 (图 24)内对智能自动真空吸尘器进行导航。

注意: 当您手动驱动智能自动真空吸尘器靠近有高度差的地方和楼梯时，请小心谨慎。

注意: 吸尘功能和侧毛刷只有在智能自动真空吸尘器向前驱动时才可用。 左右或后退按钮仅用于操纵智能自动真空吸尘器。

使用清洁时间按钮

- 默认情况下，智能自动真空吸尘器以自动清洁模式进行清洁，直至充电电池的电量不足。 智能自动真空吸尘器随后将自动返回其底座。 如果您选择了其他某个清洁时间（参见下方），您可以按遥控器 (图 25)上的最长清洁时间按钮切换回默认模式。
- 遥控器上的其他清洁时间按钮可使智能自动真空吸尘器分别 (图 26)运行 60、45 和 30 分钟。 显示屏上的清洁时间标志将显示清洁时间设置。 清洁时间结束后，智能自动真空吸尘器会返回其底座。 显示屏上的插接图标将变为亮蓝色。
- 如果您不希望智能自动真空吸尘器在清洁时间结束之后返回到底座，请按两次清洁时间按钮。 插接图标将从显示屏上消失。 清洁时间结束时，智能自动真空吸尘器就会停止工作。

操作底座

设置时钟时间和日期

如果您要使用清洁程序，则必须先在底座显示屏上设置时钟时间和星期几。

注意: 要查看以下步骤的图片，请参阅本手册的背面。

1 按设置按钮。 设置模式标志和时钟时间标志将开始闪烁。
2 按选择按钮一次。 小时显示开始闪烁。
3 使用底座上的 + 和 - 按钮设置小时。显示屏上会显示设置的小时。
4 按选择按钮确认小时设置。 分钟显示将开始闪烁。
5 使用底座上的 + 和 - 按钮设置分钟。 显示屏上会显示设置的分钟。
6 按选择按钮确认分钟设置。 表示星期日的“Su”显示将开始闪烁。
7 使用底座上的 + 和 - 按钮可设置当前星期几。
8 按选择按钮可确认星期几。
9 按设置按钮可确认时钟时间和星期几设置。 设置模式标志和时钟时间标志将停止闪烁，然后持续亮起。

设定清洁时间

如果您已经在底座显示屏上设置了时间和星期几，则可以为智能自动真空吸尘器设定清洁时间。

注意: 要查看以下步骤的图片，请参阅本手册的背面。

可用设定选项:

设定	显示屏上的指示
每天清洁	全天指示亮起

设定	显示屏上的指示
工作日清洁	周一至周五指示亮起
连续清洁 2 天	2 天指示亮起，例如周五和周六
一周清洁 1 天	选定的日期指示亮起

1 按设置按钮。 设置模式标志和清洁设定标志将开始闪烁。
2 按选择按钮一次。 小时显示开始闪烁。
3 使用底座上的 + 和 - 按钮设置小时。 显示屏上会显示设置的小时。
4 按选择按钮确认小时设置。 分钟显示将开始闪烁。
5 使用底座上的 + 和 - 按钮设置分钟。 显示屏上会显示设置的分钟。
6 按选择按钮确认分钟设置。 表示星期日的“Su”显示将开始闪烁。
7 使用底座上的 + 和 - 按钮可在清洗程序之间切换（有关可用设定选项，请参阅上表）。
8 按选择按钮确认选定的程序。
9 按设置按钮确认设定。 设置模式标志和清洁程序标志停止闪烁，然后持续亮起。
10 设置清洁程序后，显示屏会显示选定的清洁程序标志和日期。 如果使智能自动真空吸尘器处于待机状态且充电电池已充满电，其便会在设定日期的设定时间开始清洁。

风速按钮

您可以使用风速按钮将风速提升至强力或关闭风叶。 默认设置为正常风速 (图 27)。
1 按此按钮可关闭风叶。
2 按此按钮以正常速度启动风叶。
3 强力风叶按钮可提高风速。

使用干巾附件

干巾附件是一项可以使用干巾清洁硬地板的功能。

注意： 如果您使用干巾附件，则智能自动真空吸尘器可能会很难跨越门槛或爬上地毯。

干巾附件使用准备

将智能自动真空吸尘器翻转过来，置于地板或桌子上。
1 将干巾置于桌上，将干巾附件放在干巾上，固定凸缘朝向自己 (图 28)。
2 将干巾两端围绕干巾附件折起来，将固定块按入凹槽 (图 29)，将干巾固定在附件上。
3 将干巾附件的凸缘插入智能自动真空吸尘器一侧滚轮后面的开口并推入，直至其“咔哒”一声锁定到位。然后，在另一侧 (图 30)重复这些动作。
4 将智能自动真空吸尘器翻转过来放在地板上，使带有干巾附件的滚轮接触地板。

使用带干巾附件的智能自动真空吸尘器

装上干巾附件后，便可以在所有硬地板上以任何模式使用智能自动真空吸尘器。 不要在地毯或小地毯上使用干巾附件。

拆卸干巾附件

1 擦净地板后便可以卸下干巾附件。 若要卸下，将智能自动真空吸尘器翻转过来，置于地板或桌子上。
2 将干巾附件的一端向智能自动真空吸尘器另一侧的滚轮方向推动即可将其释放。 然后，拉出干巾附件。
3 如果干巾太脏无法再次使用，拉出干巾附件的固定块，并将干巾丢弃。

注意： 干巾不能漂洗或清洗。

使用隐形墙（仅限 FC8822）

您可以使用隐形墙防止智能自动真空吸尘器进入您不想让其接近的房间或区域。

将电池装入隐形墙内

隐形墙使用四节 AA 电池。

1 推动后盖底部的两个释放钮 (1)，将后盖向上滑动，从隐形墙上取下 (2) (图 32)。
2 拆开四节 AA 电池的包装，将其装入隐形墙 (图 33)的电池仓。

注意： 确保电池的 + 和 - 极方向正确。

3 将后盖重新 (图 34)滑入隐形墙。

定位隐形墙以阻止智能自动真空吸尘器

1 将装置置于您不想让智能自动真空吸尘器跨越的位置，例如，如果您想禁止吸尘器 (图 35)进入某房间，即可将其安装在该房间打开的房门上。
2 用隐形墙 (图 36)顶部的开/关滑钮将其打开。
3 启动智能自动真空吸尘器。
4 当智能自动真空吸尘器距离隐形墙过近时，隐形墙上的指示灯将开始闪烁，同时其会发射红外光束。 该红外光束可使智能自动真空吸尘器改变移动路线，远离隐形墙 (图 37)。

注意： 如果您使用隐形墙，请定期检查电池是否仍电量充足。 您可以通过关闭并再次打开虚拟墙，来检查电量情况。 如果电池的电量充足，隐形墙上的 LED 会短暂亮起。

清洁和保养

清洁智能自动真空吸尘器

为保持良好的清洁效果，您必须经常清洁跌落传感器、滚轮、侧毛刷和吸口。

1 将智能自动真空吸尘器翻转过来，置于平面上
2 使用带柔软刷毛的毛刷（例如牙刷）清除跌落传感器 (图 38)上的灰尘和绒毛。

注意： 务必定期清洁跌落传感器。 如果跌落传感器变脏，智能自动真空吸尘器可能无法检测到高度差或楼梯。

3 使用软毛刷（例如牙刷）清除前轮和侧轮 (图 39)上的灰尘和绒毛。
4 要清洁侧毛刷，请抓住刷毛并将其从轴 (图 40)上取下。
5 使用柔软的毛刷（例如牙刷）或布 (图 41)清除轴和侧毛刷中的绒毛、头毛发和线头。
6 检查智能自动真空吸尘器的侧毛刷和底部是否存在可能会损坏地板的尖锐物体。
7 若要卸下 TriActive XL 吸嘴，将手指伸入智能自动真空吸尘器底部的导槽。 有两个指向这些导槽的箭头。按下固定 TriActive 吸嘴的栓钩，使其从导槽 (1) 上松开。 然后提起 TriActive 吸嘴，将其从智能自动真空吸尘器 (2) (图 42) 上取下。
8 用软刷（例如牙刷 (图 43)）清洁吸口。
9 清除 TriActive 吸嘴上所有目视可见的灰尘，然后再将其放回。
10 要放回 TriActive 吸嘴，先将正面的小凸缘插入前轮 (1) 一侧的小槽。 然后按下 TriActive 吸嘴的栓钩，将其锁入智能自动真空吸尘器 (2) 底部的导槽。 最后，检查吸嘴是否仍然可以自由 (图 44)上下移动几毫米。
11 再次 (图 8)将侧毛刷推入智能自动真空吸尘器底部的轴上。

倒空并清洁集尘盒

集尘盒已满指示灯持续亮起时，倒空并清洁集尘盒。

1 取下盖子。
2 向上拉集尘桶盖手柄，从集尘桶仓中提出集尘桶。

注意： 取下或重新插入集尘盒时，小心不要损坏马达风叶的刀片。

3 小心地提起集尘桶的盖子 (1) 并取出滤网 (2) (图 45)。

4 在垃圾箱上晃动集尘桶将其倒空。 用布或软毛牙刷清洁滤网和集尘盒内部。 另外清洁集尘桶底部的吸口。

警告： 切勿用水或在洗碗机中清洁集尘盒和滤网。

5 将滤网放回集尘盒中 (1)。 然后将盖子放在集尘桶上 (2) (图 47)。

6 将集尘桶放回集尘桶仓，盖好吸尘器 (图 48)的上盖。

警告： 务必确保集尘盒内已放置好滤网。 如果您在集尘盒内未放置滤网的情况下使用智能自动真空吸尘器，马达会受损。

订购配件

要购买附件或备件，请访问 www.shop.philips.com/service 或联系您的飞利浦经销商。 您还可以联系所在国家/地区的飞利浦客户服务中心（请参阅全球保修卡了解详细联系信息）。

更换

更换滤网

如果滤网很脏或已损坏，请进行更换。 您可以订购新的滤网套件，型号为 FC8066。 有关如何从集尘盒中取出滤网以及如何将滤网放入集尘盒的说明，请参阅“清洁和保养”一章中的“倒空并清洁集尘盒”。

更换侧毛刷

一段时间后，请更换侧毛刷，以确保正常的清洁效果。

发现磨损或损坏迹象时务必更换侧毛刷。 另外，建议您同时更换两个侧毛刷。 您可以订购更换套件 FC8068，其中包含了备用侧毛刷。 该套件还包含两个滤网和三个干巾附件。

1 如需更换侧毛刷，请抓住旧侧毛刷的刷毛将其从轴 (图 40)上拆下。

2 将新侧毛刷推到轴 (图 8)上。

更换干巾

您可以订购新的干巾。 更换套件 FC8068 中包含了干巾， 以及两个侧毛刷和两个滤网。

更换遥控器的电池

遥控器由 CR2025 纽扣电池供电。 按遥控器上的按钮，智能自动真空吸尘器不再响应时，请更换电池。

1 将遥控器翻转过来。 推电池仓上的释放钮，同时将电池仓从遥控器 (图 49)中滑出。

2 从电池仓中取出电量耗尽的电池，装入新电池。 然后将电池仓滑回遥控器 (图 50)。

更换充电电池

只有具备资格的服务工程师，才能更换智能自动真空吸尘器的充电电池。 当充电电池无法继续充电或耗电很快时，请将智能自动真空吸尘器送往授权的飞利浦服务中心，以更换电池。 您可以在国际保修卡或 www.philips.com/support 上找到您所在国家/地区的飞利浦客户服务中心的详细联系信息。

回收

- 弃置本产品时，请不要将其与一般生活垃圾放在一起，应将其交给政府指定的回收中心。 这样做将有利于环保。
- 此产品包含内置充电电池：请勿将充电电池与一般生活垃圾一起弃置。 请您将产品送到官方收集中心或飞利浦服务中心，请专业人士移除充电电池。
- 遵循您的国家/地区有关分类回收电子电气产品和充电电池的规定。 正确弃置产品有助于避免对环境和人类健康造成不良后果。

拆下充电电池

警告： 必须在丢弃产品前取出充电电池。在取出电池时请确保电池电量已耗尽并与电源断开连接。

按照以下步骤拆下充电电池。 您也可以将智能自动真空吸尘器送往飞利浦服务中心，由其拆下充电电池。 您可联系所在国家/地区的飞利浦客户服务中心，获取您附近的服务中心地址。

1 启动智能自动真空吸尘器时，应将其置于房间内，不可从底座上启动智能自动真空吸尘器。
2 让吸尘器运转，直至充电电池电量完全耗尽，以确保在您取出并弃置充电电池前，其已完全放电。
3 拧下电池仓的螺丝，然后取下仓盖 (图 51)。
4 取出充电电池并断开连接 (图 52)。
5 将智能自动真空吸尘器和充电电池送往电子电器垃圾回收点。

故障处理方法

本章归纳了使用本产品时最常见的一些问题。 如果您无法根据以下信息解决问题，请访问 www.philips.com/support 查阅常见问题列表，或联系您所在国家/地区的客户服务中心。

故障处理方法

问题	可能的原因	解决方法
按启动/停止按钮时智能自动真空吸尘器无法开始清洁。	充电电池的电量已耗尽。	为充电电池充电。
智能自动真空吸尘器无法正确清洁。	一个或两个侧毛刷的刷毛已变形或弯曲。	将毛刷在温水中浸泡一会儿，并将其置于平面上晾干，然后再重新装入智能自动真空吸尘器。 如果这样做不能使刷毛复原，则更换侧毛刷 (请参见 '更换侧毛刷')。
	集尘盒中的滤网变脏。	用布或软毛牙刷清洁集尘盒中的滤网。您还可以在低吸力设置下使用普通真空吸尘器清洁滤网和集尘盒。
		如果刷洗或吸尘无助于清洁滤网，请用新滤网更换。 我们建议您至少每年更换一次滤网。
	集尘盒底部吸口被堵塞。	清洁吸口 (请参见 '清洁和保养')。
	前轮被毛发或其他污垢卡住。	清洁前轮 (请参见 '清洁和保养')。

问题	可能的原因	解决方法
	智能自动真空吸尘器在清洁颜色极深或有光泽的地面时会触发跌落传感器。这将导致智能自动真空吸尘器沿异常的方向图移动。	按启动/关闭按钮，然后将智能自动真空吸尘器移至颜色较浅的地板。 如果在颜色较浅的地板上问题仍然存在，请访问 www.philips.com/support 或联系您所在国家/地区的客户服务中心。
	智能自动真空吸尘器正在清洁强烈反射太阳光的地板。这可能会触发跌落传感器，导致智能自动真空吸尘器沿异常的方向图移动。	关闭窗帘，阻止太阳光射入房间。 您还可以在阳光不那么明亮时开始清洁。
开/关按钮持续亮起红色，显示屏上显示错误代码。	智能自动真空吸尘器正在发出错误信号。	查看错误代码表，了解代码 (请参见 '错误代码')的含义。
智能自动真空吸尘器在绕圈运动。	智能自动真空吸尘器处于螺旋模式。	这属于正常现象。 在地板上检测到大量灰尘时，可能会激活螺旋模式以进行彻底清洁。 这也是自动清洁模式的一部分。 大约一分钟后，智能自动真空吸尘器恢复正常清洁模式。 您还可以通过在遥控器上选择其他清洁模式来停止螺旋模式。
智能自动真空吸尘器无法找到底座。	没有足够的空间供智能自动真空吸尘器导航到底座。	请尝试将底座 (请参见 '安装底座')放置到其他地方。
	智能自动真空吸尘器仍在积极搜索。	给智能自动真空吸尘器约 20 分钟时间让其返回到底座。
	您可能按了两次清洁时间按钮，禁用了智能自动真空吸尘器的自动插接功能。 在这种情况下，显示屏上看不到插接图标，当清洁时间结束时，智能自动真空吸尘器便会停止工作。	按住启动/停止按钮 5 秒钟可重新启动智能自动真空吸尘器。 插接功能将自动重新启用。 您也可以按两次清洁时间按钮来重新启用插接功能。插接图标将重新出现在显示屏上。 若要让智能自动真空吸尘器返回到底座，按插接按钮。

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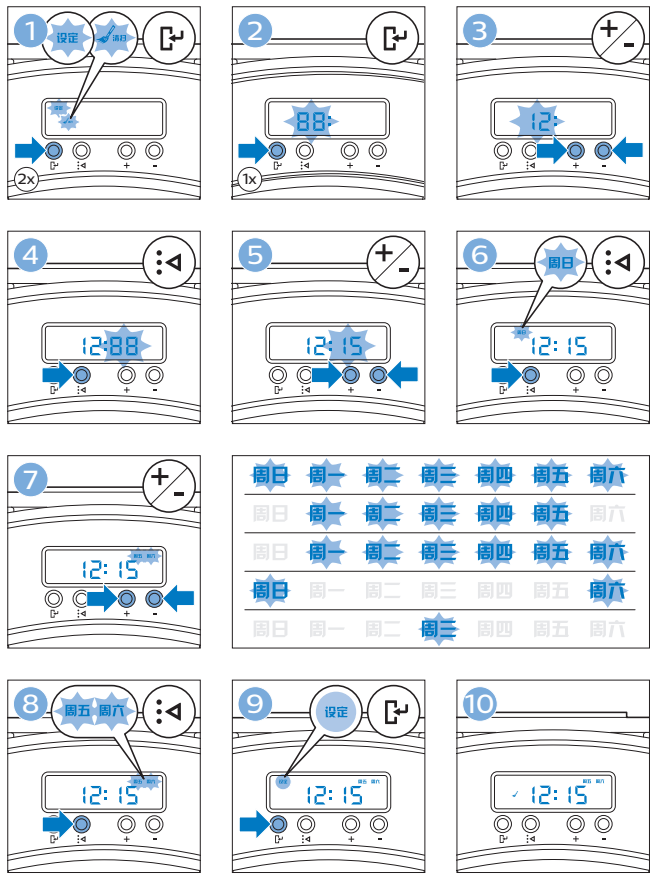
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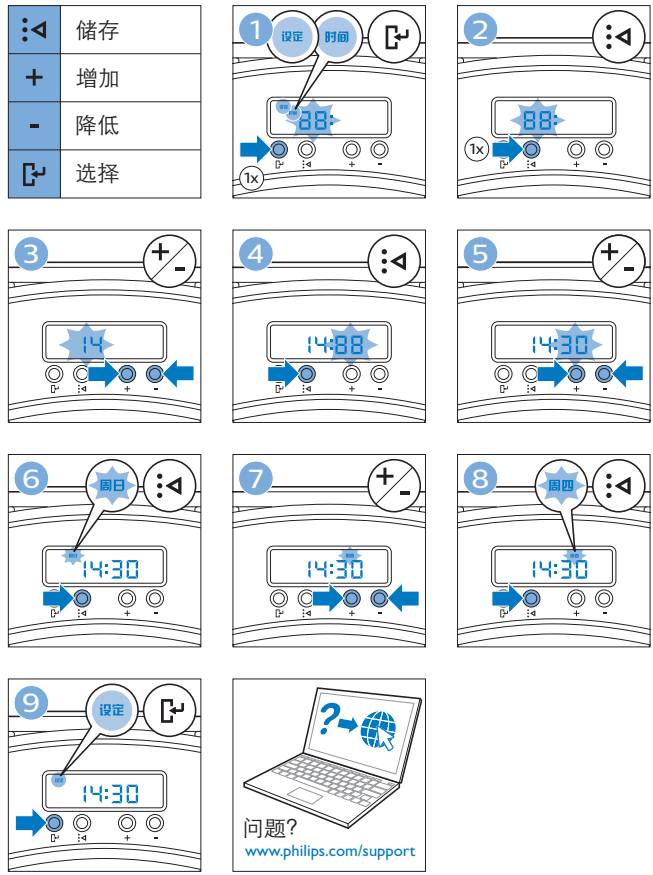

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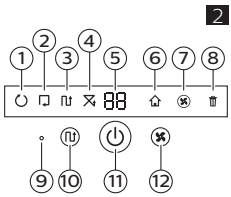
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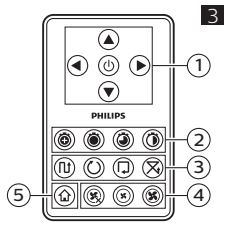
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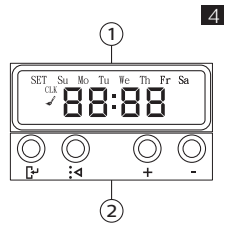
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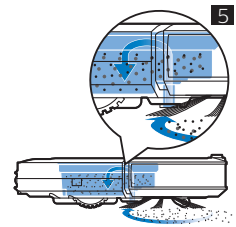
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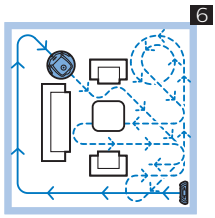
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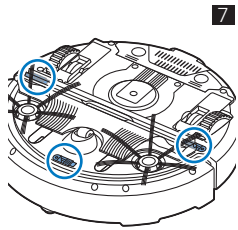
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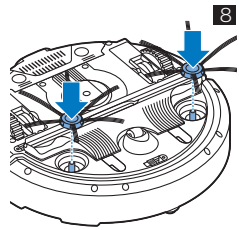
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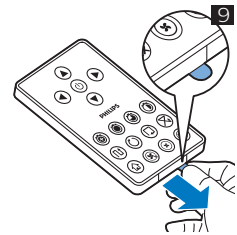
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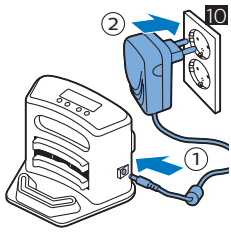
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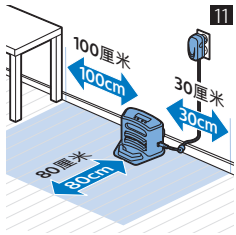
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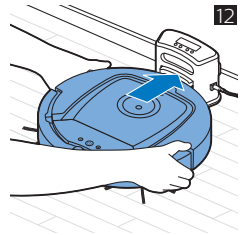
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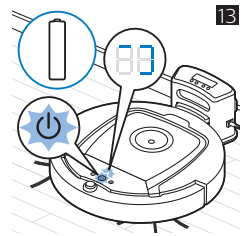
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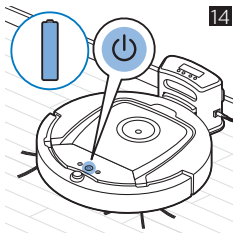
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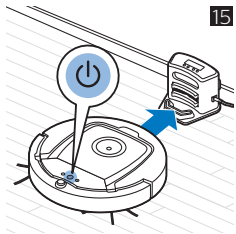
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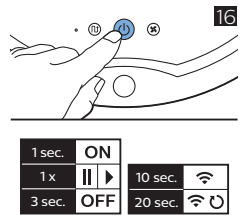
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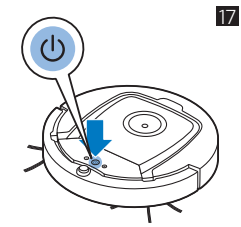
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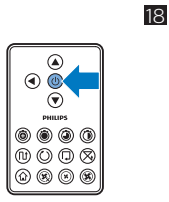
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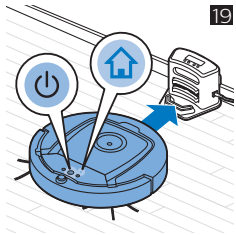
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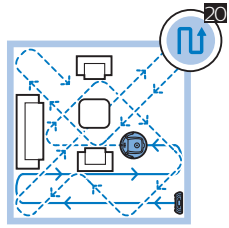
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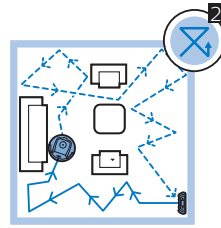
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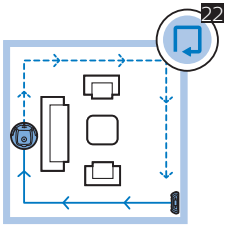
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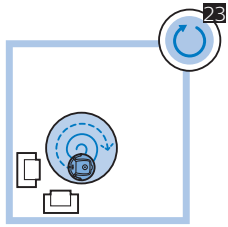
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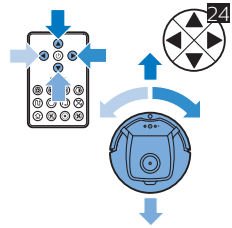
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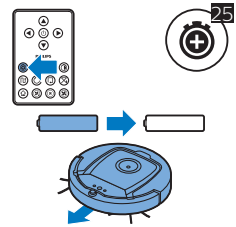
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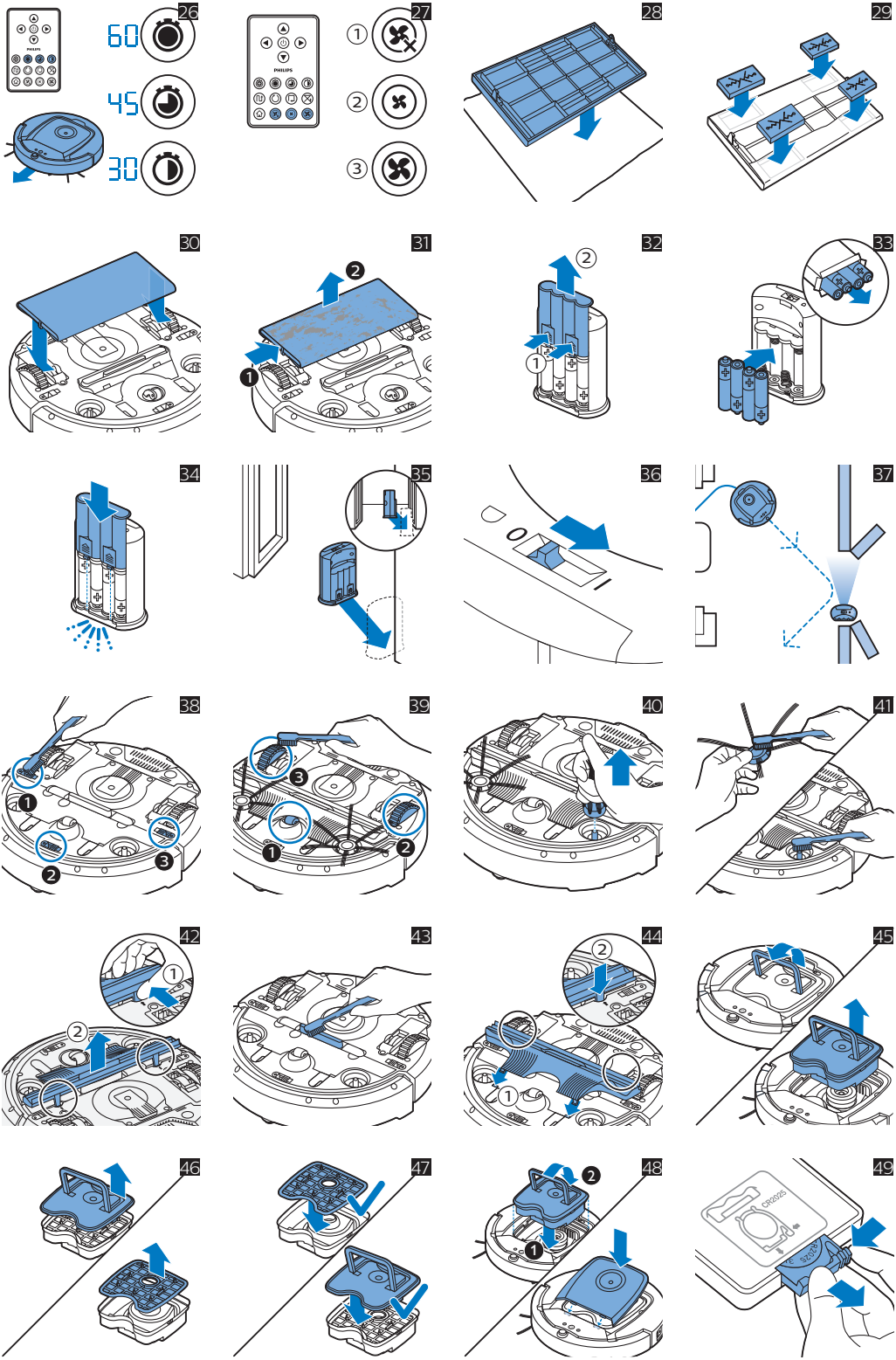
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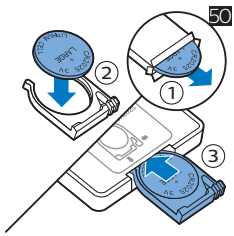
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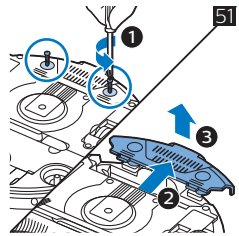
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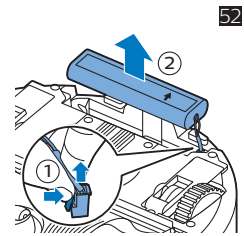
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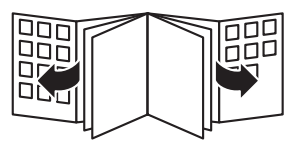

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